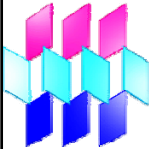


the 1st COE Postdoctoral and Doctoral  
Researchers Technical Presentation

Indoor user location system  
for ubiquitous computing



Muneyuki Sakata

Assistant Professor (COE)  
Image Processing Lab.

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Background

- Ubiquitous Computing
  - “Anyone”, “Anywhere”, “Anytime”
- Mobile Computing
  - ◆ Small devices
  - ◆ Wireless networks
- Pervasive Computing
  - ◆ ≡ Invisible Computing
  - ◆ Context-aware computing
    - Location systems : position, situation, activity



Location systems(1/2)

- Outdoor
  - GPS (Global Positioning System)
- Indoor
  - Cricket (MIT , Crossbow)
    - ◆ radio wave and ultrasound
    - High positioning accuracy
    - × Too many sensors are needed
  - Ekahau (Ekahau)
    - ◆ radio intensity from Wi-Fi access points
    - Simple infrastructure
    - × Affected by change in environment

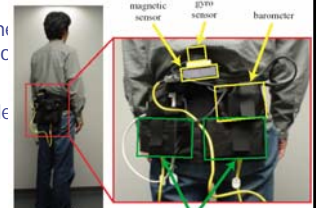
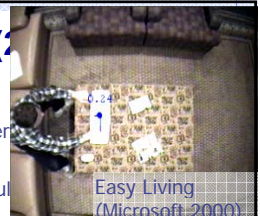


Cricket



Location systems(2)

- Autonomous positioning system (Konishi et al., Tokyo University)
  - No sensor in environment
  - × Large user's system / Accumulation of sensors
- Image processing using camera (Easy Living (Microsoft, 2000))
  - User has no devices
  - × Need some action to identify



(Konishi et al., 2001)

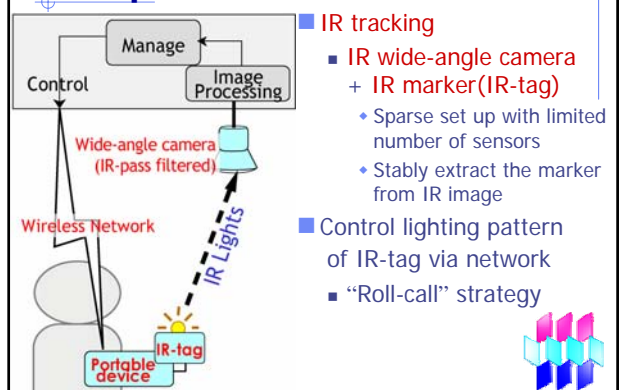
Objective

User location system for indoors

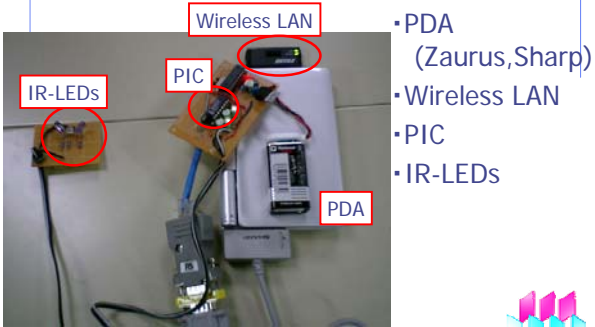
- ALTAIR (Automatic Location Tracking system using Active IR-tag)
  - Automatic tracking and identification
    - ◆ Don't disturb daily work
    - ◆ Smaller user's equipments
  - High accuracy ( ~1m )  
ex.) in front of which desk, which part of the room
  - Simple infrastructure
    - ◆ 2 cameras in an area



Proposed Method



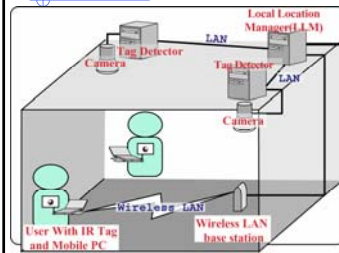
## System (user's system)



- PDA (Zaurus, Sharp)
- Wireless LAN
- PIC
- IR-LEDs



## System (for an area)



### IR wide-angle camera

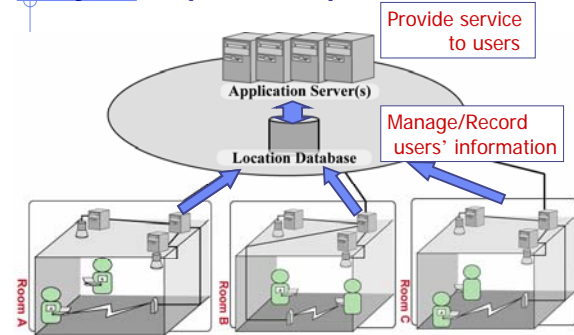
- Tracks lights of all IR-tags
- Calculates IR-tags' positions
- Detects blinking IR-tag

### Local Location-Manager(LLM):

- Merges information from cameras
- Sequentially instructs IR-tags of all users to blink
- Updates user location and identification



## System(servers)

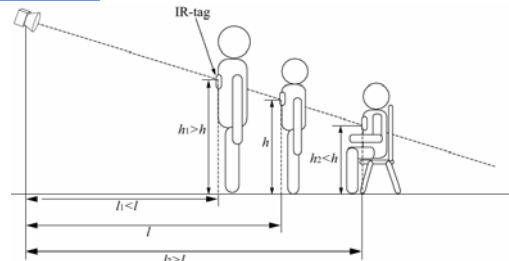


Provide service to users

Manage/Record users' information



## Changes of estimated position

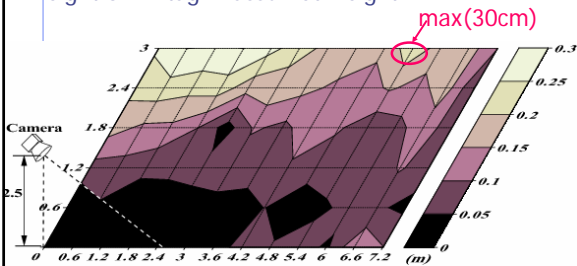


- The system uses only one IR-image for estimating position.
- The estimated position is affected by fixing point of IR-tag, and user's posture.



## Accuracy (1/2)

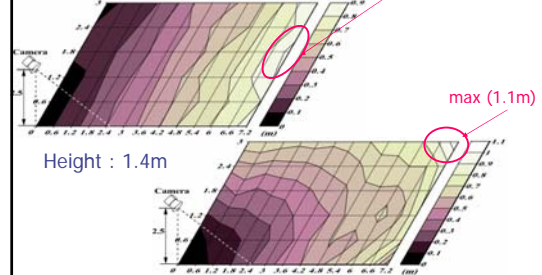
Height of IR-tag = assumed height = 1.2m



- Average : 10 cm, Max : 30 cm in 7.2m x 6m area

## Accuracy (2/2)

Height : 1.0m

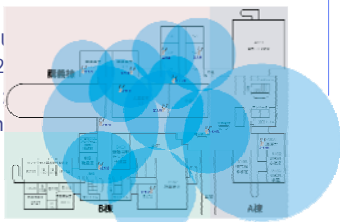


The system could detect users situation, if the height of IR-tag is changed!



## Combination with other systems

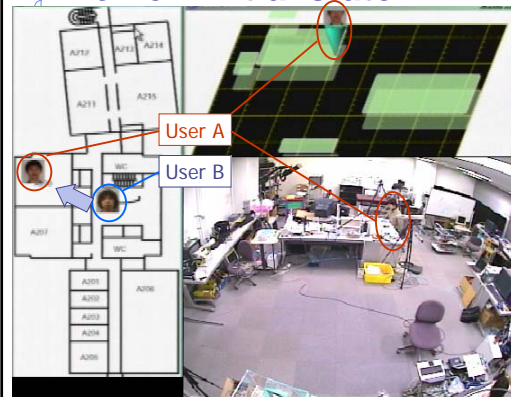
- **ALTAIR** : high accuracy
  - Each area needs 2 sensors
- **Wireless-network**
  - Which access point



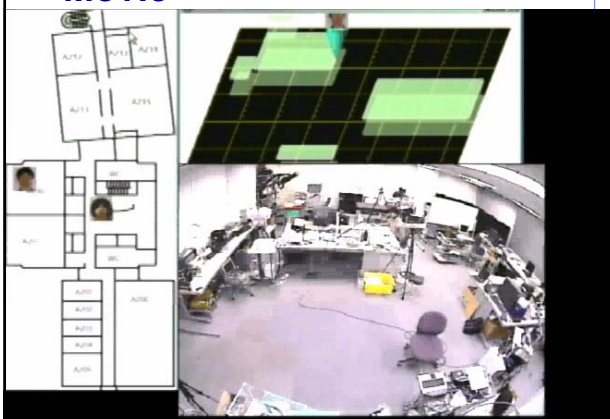
- Grant for COE young researcher 2005
  - With Mr. Tobe ( inet-lab )
  - At 1st floor in NAIST-IS building
    - Using 12 access points
    - About 10 – 30 m area for one access point



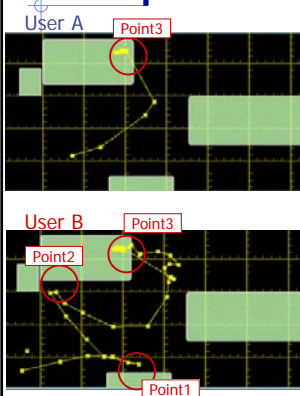
## Movie: Initial state



## Movie



## Footprints



- Plots of users' footprints
- These footprints indicate
  - User B moved to Point 3 through Point 1, Point2
  - User A walk out the area
- System could understand situation between user & object (desk, computer ...) using circle area of 1m in diameter



## Discussion

- The system can ...
  - detect user's entering and leaving area automatically
  - start and terminate tracking user automatically



The system needs no user's prearranged action in all operation of getting users' location

- By monitoring in real-time and plotting user's footprint, system can monitor and record user's activity
  - The system could analyze user's activity



## Summary

- **User location system for indoors**
  - System can get users' location **automatically**
  - Simple settings
    - 2 sensors (cameras) in one area
    - Wireless network
  - **High accuracy (~1m)**
  - System can be combined with other location systems.
    - Location system using wireless network
- Future work
  - Downsize the users' system using Zigbee devices

