

The deployment and the initial result of the Internet-Based Augmentation System for Global Navigation Satellite Systems

Information Technology Center
Osamu Tobe
(osamu-to@is.naist.jp)

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Background

- The importance of discovering geographical location information of a node increases.
 - In mobile and ubiquitous computing, the position of a node is not necessarily fixed.
- Global Navigation Satellite Systems (GNSS) is a very effective device.
 - GNSS can be used in the outdoors of the Earth.
- However, GNSS has limits on accuracy.
 - To enhance the accuracy, it is necessary for a node to receive the error correction data.

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Problems in the existing GNSS correction systems

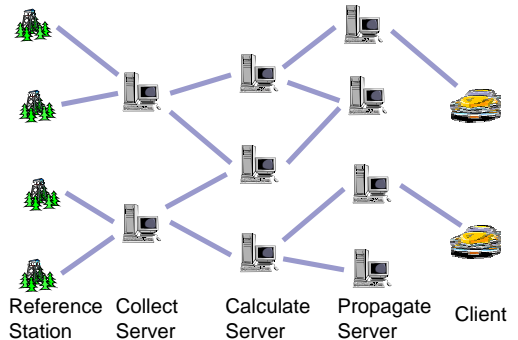
- Service Area
 - It can only cover a limited area with medium wave beacon or FM radio wave.
- Interactivity
 - It is difficult to send dedicated correction data to each user.
- Device dependency
 - Users have to use a different device for every system.

I have proposed the Internet-Based Augmentation System for GNSS (IBAS)

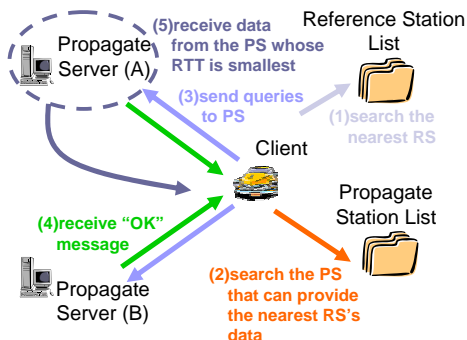
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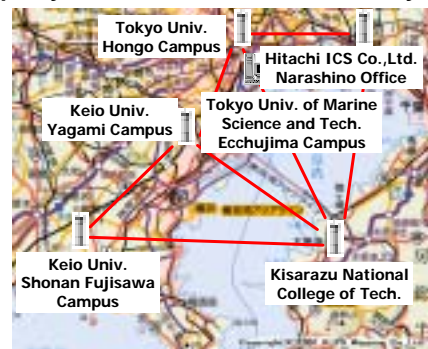
System architecture of IBAS



Flow of Server Select Mechanism



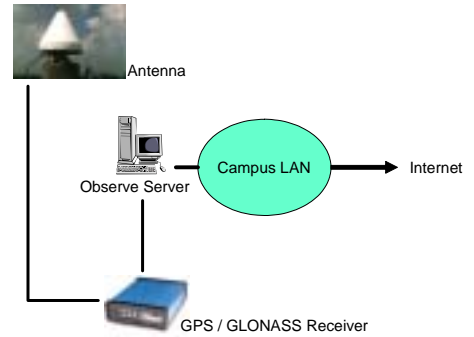
Deployments of RSs in Tokyo



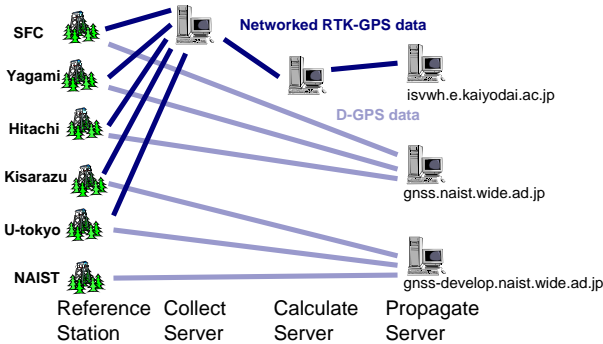
Deployments of RSs in Kansai



Configuration diagram of RS



Testbed architecture



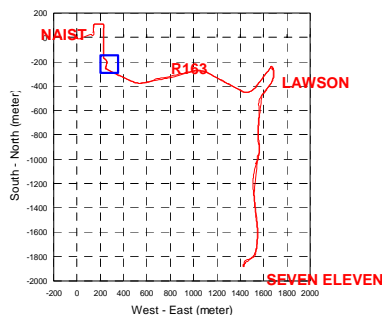
Positioning Experiment

- I observed D-GPS positioning results with IBAS during moving around NAIST by car.
 - A Client is connected with AirH^o 32k.
 - RS and PS at NAIST are selected automatically by the above-mentioned mechanism.

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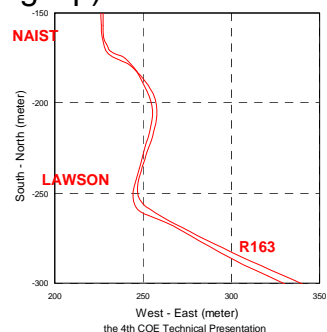
Positioning with D-GPS



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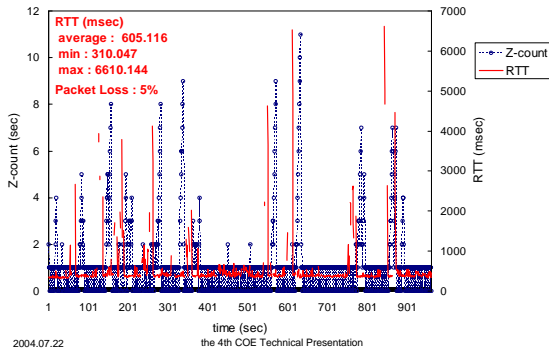
Positioning with D-GPS (Scaling Up)



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Transition of RTT and data delay



The enhancement of IBAS

- To realize higher reliability and accuracy...
 - Removal of the error ingredients from observation data
 - Various error elements are contained in observation data.
 - Networked D-GPS
 - Enabling mobile nodes to position in high accuracy even if they are moving in high speed.

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Summary

- To enable mobile nodes to locate their position in high accuracy, I proposed the Internet-Based Augmentation System for GNSS (IBAS).
- IBAS can provide dedicated GNSS error correction data with each node.
 - A user finds out the nearest RS and PS that can provide the data calculated at that RS automatically.
- I have established the testbed of IBAS.
 - A client could obtain high accuracy location information, enough to decide the lane he ran on.

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